

## Exercises NMES - 15.1.2025

### Exercise 1

Write the LU factorization, without pivoting, of:

$$\begin{matrix} (r_1) \\ (r_2) \\ (r_3) \end{matrix} \begin{bmatrix} 2 & 4 & 4 \\ 1 & 5 & 7 \\ 3 & 12 & 18 \end{bmatrix}$$

showing the intermediate computations.

**Solution:** The steps are the same as for the Gaussian elimination method. Let  $L = I_n$  and compute the entries in the first column of  $L$  while eliminating the elements in the first column of  $A$  below the diagonal:  $l_{2,1} = \frac{a_{2,1}}{a_{1,1}} = \frac{1}{2}$  and  $l_{3,1} = \frac{a_{3,1}}{a_{1,1}} = \frac{3}{2}$ . Now replace the row  $(r_2)$  and  $(r_3)$  with

$$(r_2) - l_{2,1} \cdot (r_1) = (1, 5, 7) - \frac{1}{2} \cdot (2, 4, 4) = (1, 5, 7) - (1, 2, 2) = (0, 3, 5)$$

$$(r_3) - l_{3,1} \cdot (r_1) = (3, 12, 18) - \frac{3}{2} \cdot (2, 4, 4) = (3, 12, 18) - (3, 6, 6) = (0, 6, 12)$$

respectively. Now the matrix  $A$  becomes

$$\begin{matrix} (r_1) := (r_1) \\ (r_2) := (r_2) - l_{2,1} \cdot (r_1) \\ (r_3) := (r_3) - l_{3,1} \cdot (r_1) \end{matrix} \begin{bmatrix} 2 & 4 & 4 \\ 0 & 3 & 5 \\ 0 & 6 & 12 \end{bmatrix}$$

and  $L$  is

$$\begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 3/2 & 0 & 1 \end{bmatrix}.$$

Now repeat the computations above to eliminate the portion of the second row of  $A$  below the diagonal. So  $l_{3,2} = \frac{a_{3,2}}{a_{2,2}} = 2$ ; replace now the third row  $(r_3)$  with  $(r_3) - l_{3,2}(r_2)$ .

$$(r_3) - l_{3,2} \cdot (r_2) = (0, 6, 12) - 2 \cdot (0, 3, 5) = (0, 6, 12) - (0, 6, 10) = (0, 0, 2).$$

So the matrix  $A$  has now become

$$\begin{matrix} (r_1) := (r_1) \\ (r_2) := (r_2) \\ (r_3) := (r_3) - l_{3,2} \cdot (r_2) \end{matrix} \begin{bmatrix} 2 & 4 & 4 \\ 0 & 3 & 5 \\ 0 & 0 & 2 \end{bmatrix}$$

and  $L$  is

$$\begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 3/2 & 2 & 1 \end{bmatrix}.$$

**Exercise 2**

Compute the linear regression  $r(x) = c_0 + c_1x$  for the set of points

$$(-3, 0), (-2, 0), (-1, 0), (1, 1), (2, 2), (3, 4).$$

**Solution:** To compute the solution recall the least square linear problem

$$\begin{bmatrix} m & \sum_{i=1}^m x_i \\ \sum_{i=1}^m x_i & \sum_{i=1}^m (x_i)^2 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^m y_i \\ \sum_{i=1}^m y_i x_i \end{bmatrix}.$$

which in this case is

$$\begin{bmatrix} 6 & 0 \\ 0 & 28 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 7 \\ 17 \end{bmatrix},$$

gives the solution which is

$$c_0 = \frac{7}{6}, \quad c_1 = \frac{17}{28}.$$

**Exercise 3**

Starting from  $x^{(0)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ , compute 2 iterations of the Jacobi method

applied to the system  $Ax = b$ , where

$$A = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

**Solution:** Recall that for iterative methods, we can split  $A = M - N$ , so that the general step of an iterative method is

$$x^{(k+1)} = x^{(k)} + M^{-1}r^{(k)}$$

In the case of Jacobi method,  $M = \text{diag}(A)$

$$M = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}.$$

Before starting, compute the residual  $r^{(0)}$

$$r^{(0)} = b - Ax^{(0)} = b = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

*First iteration*

Firstly, we have to compute  $M^{-1}r^{(0)}$ , which amounts to solving the linear system

$$Mu = r^{(0)}.$$

Since  $M$  is diagonal, it is easy to solve the linear system, obtaining the solution  $u$

$$u = \begin{bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix},$$

so  $x^{(1)} = x^{(0)} + u = (1/2, 0, 1/2)^T$ . Then compute the residual  $r^{(1)} = b - Ax^{(1)}$

$$r^{(1)} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{3}{2} \\ 0 \\ \frac{3}{2} \end{bmatrix} = - \begin{bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

*Second iteration*

As before, compute the solution of the linear system  $Mu = r^{(1)}$ , that yields

$$x^{(2)} = x^{(1)} + u = \begin{bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix} - \begin{bmatrix} \frac{1}{4} \\ 0 \\ \frac{1}{4} \end{bmatrix} = \begin{bmatrix} \frac{1}{4} \\ 0 \\ \frac{1}{4} \end{bmatrix}.$$

#### Exercise 4

Apply two bisection iterations to solve the equation

$$x^3 + 3x - 2 = 0 \quad \text{in } [0, 1].$$

**Solution:** Let  $F(x) = x^3 + 3x - 2$ . We are looking the solution in the interval  $[0, 1]$ , so first check that  $F(0)$  and  $F(1)$  have different sign. Indeed

$$F(0) = -2, \quad F(1) = 2$$

.

*First iteration.*

We start with  $a = 0$  and  $b = 1$ . Compute the midpoint  $m = \frac{a+b}{2}$ , and evaluate  $F(m)$ .

$$m = \frac{1}{2}, \quad F(m) = \frac{1}{8} + \frac{3}{2} - 2 = -\frac{3}{8}.$$

Therefore, since  $F(m) < 0$ , replace update  $a$ ,  $a := m$ .

*Second iteration.*

Compute the midpoint  $m = \frac{a+b}{2}$  and evaluate  $F(m)$ .

$$m = \frac{3}{4}, \quad F(m) = \frac{27}{64} + \frac{9}{4} - 2 = \frac{43}{64}.$$

Since,  $F(m) > 0$ , then for the next iteration we update  $b$ ,  $b := m$ .

### Exercise 5

With initial guess  $\underline{x}^{(0)} = [1, 1]^T$  apply one Newton iteration to find an approximate solution of the system

$$\underline{F}(\underline{x}) = \begin{bmatrix} x_1^2 - 2x_1 + x_2 + 7 \\ 2x_1 - x_2 + 2 \end{bmatrix}.$$

**Solution:** Recall that the Newton's iteration for multivariate functions is given by

$$\underline{x}^{(k+1)} = \underline{x}^{(k)} - \left( J_F(\underline{x}^{(k)}) \right)^{-1} \cdot \underline{F}(\underline{x}^{(k)}),$$

where  $J_F$  is the Jacobian matrix of  $\underline{F}$ . We have

$$J_F(\underline{x}) = \begin{bmatrix} \frac{\partial F_1}{\partial x_1} & \frac{\partial F_1}{\partial x_2} \\ \frac{\partial F_2}{\partial x_1} & \frac{\partial F_2}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 2x_1 - 2 & 1 \\ 2 & -1 \end{bmatrix}.$$

For  $k = 0$ , that is the first iteration, we have

$$\underline{F}(\underline{x}^{(0)}) = \begin{bmatrix} 1^2 - 2 + 1 + 7 \\ 2 - 1 + 2 \end{bmatrix} = \begin{bmatrix} 7 \\ 3 \end{bmatrix}, \quad \text{and} \quad J_F(\underline{x}^{(0)}) = \begin{bmatrix} 0 & 1 \\ 2 & -1 \end{bmatrix},$$

and we have to compute  $\underline{u} = [u_1, u_2]^T$  solution of  $J_F(\underline{x}^{(0)}) \cdot \underline{u} = \underline{F}(\underline{x}^{(0)})$ . The solution of this linear system is

$$\begin{cases} u_2 = 7 \\ 2u_1 - u_2 = 3 \end{cases} \rightarrow \begin{cases} u_2 = 7 \\ u_1 = \frac{3+7}{2} = 5 \end{cases}$$

and the first newton iteration step gives

$$\underline{x}^{(1)} = \underline{x}^{(0)} - \underline{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 5 \\ 7 \end{bmatrix} = - \begin{bmatrix} 4 \\ 6 \end{bmatrix}.$$

### Exercise 6

Given the function  $f(x) = \cos(2\pi x)$  compute its Lagrange interpolant of degree 2 through the points  $x_1 = 0$ ,  $x_2 = 1/2$ ,  $x_3 = 1$ .

**Solution 1:** Recall that the Lagrange interpolant of  $f$  of degree  $k$ , over the points  $x_1, x_2, \dots, x_{k+1}$ , is

$$\Pi_k(f) := \sum_{i=1}^{k+1} f(x_i)L_i(x), \quad \text{where} \quad L_i(x) := \prod_{\substack{j=1 \\ j \neq i}}^{k+1} \frac{(x - x_j)}{(x_i - x_j)}.$$

In order to compute  $\Pi_2(f)$  on the points  $x_1, x_2, x_3$ , we have

$$\begin{aligned} L_1(x) &= \frac{(x - x_2)(x - x_3)}{(x_1 - x_2)(x_1 - x_3)} = \frac{(x - \frac{1}{2})(x - 1)}{(-\frac{1}{2})(-1)} = (2x - 1)(x - 1), \\ L_2(x) &= \frac{(x - x_1)(x - x_3)}{(x_2 - x_1)(x_2 - x_3)} = \frac{(x - 0)(x - 1)}{(\frac{1}{2})(-\frac{1}{2})} = -4x(x - 1), \\ L_3(x) &= \frac{(x - x_1)(x - x_2)}{(x_3 - x_1)(x_3 - x_2)} = \frac{(x - 0)(x - \frac{1}{2})}{(1)(\frac{1}{2})} = x(2x - 1), \end{aligned}$$

and also

$$\begin{aligned} f(x_1) &= \cos(2\pi x_1) = \cos(0) = 1, \\ f(x_2) &= \cos(2\pi x_2) = \cos(\pi) = -1, \\ f(x_3) &= \cos(2\pi x_3) = \cos(2\pi) = 1. \end{aligned}$$

Finally

$$\begin{aligned} \Pi_2(f) &= f(x_1)L_1(x) + f(x_2)L_2(x) + f(x_3)L_3(x) \\ &= 1 \cdot (2x - 1)(x - 1) + (-1) \cdot (-4x)(x - 1) + 1 \cdot x(2x - 1) \\ &= 2x^2 - 2x - x + 1 + 4x^2 - 4x + 2x^2 - x \\ &= 8x^2 - 8x + 1. \end{aligned}$$

**Solution 2:** An alternative solution consists in the following observation.  $\Pi_2(f)$  is the degree two polynomial  $c_1 + c_2x + c_3x^2$ , where the coefficients  $c_1, c_2, c_3$  are solution of the following linear system

$$\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} f(x_1) \\ f(x_2) \\ f(x_3) \end{bmatrix}$$

For this exercise we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & \frac{1}{2} & \frac{1}{4} \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

In particular  $c_1 = 1$  and it remains to solve

$$\begin{cases} 2c_2 + c_3 = -8 \\ c_2 + c_3 = 0 \end{cases} \rightarrow \begin{cases} 2c_2 + c_3 = -8 \\ c_3 = -c_2 \end{cases} \rightarrow \begin{cases} c_2 = -8 \\ c_3 = 8 \end{cases}$$

Again we found that  $\Pi_2(f) = 1 - 8x + 8x^2$ .

### Exercise 7

Describe the Crank-Nicolson scheme for the solution of an ODE and explain its relation with the trapezoidal quadrature rule. Then, compute one step of the Crank-Nicolson scheme for the problem

$$\begin{cases} y'(t) = 2t(1 - y(t)) \\ y(0) = 3 \end{cases}$$

selecting  $\Delta t = 1$ .

**Solution:** Let  $t_n = t_0 + n\Delta t$  and  $y_n = y(t_n)$ . We are given  $t_0 = 0$  and  $\Delta t = 1$ , and have to compute one step of Crank-Nicolson, i.e. compute  $y_1$ , for  $t_1 = 1$ .

For the Crank-Nicolson scheme, we approximate the derivative using a finite difference and the ODE field with the average of the fields at two consecutive timesteps

$$\frac{y_n - y_{n-1}}{\Delta t} = \frac{1}{2}(f(t_n, y_n) + f(t_{n-1}, y_{n-1})).$$

In our case,  $f(t, y) = 2t(1 - y)$  and  $\Delta = 1$ , therefore

$$y_n - y_{n-1} = \frac{1}{2}(2t_n(1 - y_n) + 2t_{n-1}(1 - y_{n-1})).$$

In order to compute  $y_1$ , substitute  $t_0, t_1, y_0$  in the equation above and solve for  $y_1$ .

$$\begin{aligned} y_1 - y_0 &= \frac{1}{2}(2t_1(1 - y_1) + 2t_0(1 - y_0)) \\ y_1 - 3 &= \frac{1}{2}(2 \cdot 1 \cdot (1 - y_1) + 2 \cdot 0 \cdot (1 - 3)), \end{aligned}$$

to obtain  $y_1 = 2$ .