

A weak formulation for a dynamic process in delamination
with unilateral constraints

Riccardo Scala

WIAS
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Introduction: setting

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The variable $u : \Omega \rightarrow \mathbb{R}^d$ represents the displacement. The variable $z : \Gamma \rightarrow [0, 1]$ represents the status of the adhesive.

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The variable $\sigma : \Omega \rightarrow \mathbb{R}^{d \times d}$ is the stress of the body. The constitutive equation for σ is

$$\sigma = \mathbb{C}^0 e(u) + \mu \mathbb{C}^1 e(\dot{u}),$$

where $e(u) := \frac{1}{2}(\nabla u + \nabla u^T)$, \mathbb{C}^0 is the elastic tensor and \mathbb{C}^1 is the elastic tensor for viscosity, $\mu > 0$ is the viscosity of the material. We suppose \mathbb{C}^i positive definite and constant on Ω (homogeneous material).

The general problem

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If $f : \Omega \rightarrow \mathbb{R}^d$, $g : \partial_N\Omega \rightarrow \mathbb{R}^d$ represents the external forces, and $w : \partial_D\Omega \rightarrow \mathbb{R}^d$ a boundary datum, then the law of dynamic reads

$$\rho\ddot{u} - \text{Div } \sigma = f$$

where ρ is the constant density of the material, coupled with the Neumann condition $\sigma\nu = g$ on $\partial_N\Omega$, and the Dirichlet condition $u = w$ on $\partial_D\Omega$.

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The relation with the variable z arises in the condition

$$\sigma\nu = -\mathbb{K}[u]z \quad \text{on } \Gamma$$

where \mathbb{K} is the (constant, positive definite) elastic tensor of the adhesive, and $[u] := u^2 - u^1$.

Let us introduce the delamination potential

$$\frac{1}{2} \int_{\Gamma} \mathbb{K}[u] \cdot [u]z.$$

The internal variable

As for the constitutive equations for $z \in L^\infty(\Gamma, [0, 1])$, we want that the process of deterioration is irreversible:

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$$\dot{z} \leq 0. \quad (1)$$

Moreover there is a delamination threshold $\alpha \in L^\infty(\Gamma)$, with $\alpha > c > 0$, such that

$$\frac{1}{2}\mathbb{K}[\mathbf{u}] \cdot [\mathbf{u}] < \alpha \quad \Rightarrow \quad \dot{z} = 0 \quad (2a)$$

$$(2b)$$

and

$$\dot{z}\left(\frac{1}{2}\mathbb{K}[\mathbf{u}] \cdot [\mathbf{u}] - \alpha\right) = 0, \quad (2c)$$

$$\frac{1}{2}\mathbb{K}[\mathbf{u}] \cdot [\mathbf{u}] - \alpha \leq 0, \quad (2d)$$

holding on the set $\{z > 0\} \subset \Gamma$.

Introduction of the constraint

Physically, the condition $[u] \cdot \nu$ is the normal jump of the displacement on Γ . Thus if it is positive, means that the bodies are separating, while a negative value must be avoided, since it means that interpenetration of matter is taking place.

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The presence of (3) will provide an instantaneous normal reaction at Γ as soon as $[\mathbf{u}] \cdot \boldsymbol{\nu} = 0$. Such reaction must have fixed sign too!

So we introduce the reaction term ξ in the equation for σ , i.e.,

$$-\sigma(t)\boldsymbol{\nu} = \mathbb{K}[\mathbf{u}(t)]\mathbf{z}(t) + \xi\boldsymbol{\nu} \quad \text{on } \Gamma, \quad (4)$$

coupled with (3) and the condition

$$[\mathbf{u}] \cdot \boldsymbol{\nu} > 0 \quad \Rightarrow \quad \xi = 0, \quad (5)$$

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This can be equivalently said writing

$$\xi \in \partial I_{[0,+\infty)}([\mathbf{u}] \cdot \boldsymbol{\nu}), \quad (7)$$

with $\partial I_{[0,+\infty)}$ denotes the subdifferential of the characteristic function of the interval $[0, +\infty)$.

Simplifications (WLOG) and Generalizations

We treat the homogeneous Dirichlet datum case $u = 0$ on $\partial_D \Omega$. Moreover we assume all the elasticity tensors being the identity matrix, i.e., $\mathbb{C}^1 = \mathbb{C}^2 = \mathbb{K} = \text{Id}$, and the constant $\rho = \mu = 1$. Finally we replace the symmetric gradient $e(u)$ by the usual one ∇u (wlog thanks to Korn).

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Let us rewrite all the equations

$$\ddot{u} - \Delta u - \Delta \dot{u} = f \quad \text{on } \Omega, \quad (8a)$$

$$- (\nabla u + \nabla \dot{u}) \nu = [u]z + \xi \nu \quad \text{on } \Gamma, \quad (8b)$$

$$\frac{1}{2} |[u]|^2 < \alpha \quad \Rightarrow \quad \dot{z} = 0, \quad (8c)$$

and

$$\dot{z} \left(\frac{1}{2} |[u]|^2 - \alpha \right) = 0, \quad (8d)$$

$$\frac{1}{2} |[u]|^2 - \alpha \leq 0, \quad (8e)$$

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On the other side, in order to get a general constraint, we replace the function $I_{[0, +\infty)}$ by $j : \mathbb{R} \rightarrow [0, +\infty]$, being a convex and lower semicontinuous function such that $j(0) = \min j = 0$. Then the constraint reads

$$\xi \in \partial j([u] \cdot \nu). \quad (8f)$$

We define

$$\mathcal{J}(v) := \int_0^T \int_{\Gamma} j(v) dx dt \quad v \in L^2([0, T] \times \Gamma). \quad (9)$$

The subdifferential of \mathcal{J} on $L^2([0, T] \times \Gamma)$ is defined as the multivalued operator

$$\partial \mathcal{J} : L^2([0, T] \times \Gamma) \rightrightarrows L^2([0, T] \times \Gamma),$$

as follows: for $v, u \in L^2([0, T] \times \Gamma)$, we have

$$v \in \partial \mathcal{J}(u) \Leftrightarrow \mathcal{J}(w) - \mathcal{J}(u) \geq \langle v, w - u \rangle \quad \forall w \in L^2([0, T] \times \Gamma). \quad (10)$$

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Setting $\beta := \partial j$, it is easy to see that $v \in \partial \mathcal{J}(u)$ if and only if

$$v(t, x) \in \beta(u(t, x)) \quad \text{for a.e. } (t, x) \in [0, T] \times \Gamma. \quad (11)$$

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We call this the pointwise interpretation of $\partial \mathcal{J}$, so we still denote it by $\beta := \partial \mathcal{J}$.

Relaxation of the constraint

We consider the restriction of \mathcal{J} to the space $\mathcal{H} \subset L^2([0, T] \times \Gamma)$, and we consider the subdifferential with respect to this new topology. This is the multivalued operator

$$\partial_{\mathcal{H}}\mathcal{J} : \mathcal{H} \rightrightarrows \mathcal{H}',$$

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Note that the pointwise interpretation

$$\xi(t, x) \in \beta(u(t, x)) \quad \text{for a.e. } (t, x) \in [0, T] \times \Gamma,$$

does no longer make sense!

Properties of the weak constraint

However if $\xi \in \beta_w(\mathbf{u})$ the following can be said:

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Theorem

There exists a bounded Borel measure \mathcal{T} such that $\langle\langle \xi, \varphi \rangle\rangle = \int_0^T \int_{\Gamma} \varphi d\mathcal{T}$ for all $\varphi \in \mathcal{H} \cap C_0([0, T] \times \Gamma)$. Moreover if $\mathcal{T} = \mathcal{T}_a + \mathcal{T}_s$ then

$$\mathcal{T}_a \mathbf{u} \in L^1([0, T] \times \Gamma), \quad (13)$$

$$\mathcal{T}_a(t, \mathbf{x}) \in \beta(\mathbf{u}(t, \mathbf{x})) \text{ for a.e. } (t, \mathbf{x}) \in [0, T] \times \Gamma, \quad (14)$$

$$\langle\langle \xi, \mathbf{u} \rangle\rangle - \int_0^T \int_{\Gamma} \mathcal{T}_a \mathbf{u} \, dx dt = \sup \left\{ \int_0^T \int_{\Gamma} z \, d\mathcal{T}_s, z \in C([0, T] \times \Gamma), |z| \leq 1 \right\}. \quad (15)$$

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It can be proved that, in the case that $j = I_{[0, +\infty)}$, denoting by $\mathcal{T}_s = \rho |\mathcal{T}_s|$,

$$\rho \in \partial j(\mathbf{u}) \quad |\mathcal{T}_s| - \text{a.e. in } [0, T] \times \Gamma. \quad (16)$$

This means that \mathcal{T}_s is supported on the set where $\mathbf{u} = 0$ and that here it holds $\rho = -1$.

These results are adaptations of those contained in

- H. Brézis, Intégrales convexes dans les espaces de Sobolev, *Israel J. Math.*, 13 (1972), 9–23.
- M. Grun-Rehomme, Caractérisation du sous-différentiel d'intégrandes convexes dans les espaces de Sobolev (French), *J. Math. Pures Appl.* (9), 56 (1977), 149–156.

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Recall that j^ϵ is globally ϵ^{-1} -Lipschitz continuous. As for j , we set

$$\beta^\epsilon := \partial j^\epsilon,$$

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Lemma

β^ϵ is a monotone operator on \mathcal{H} into \mathcal{H}' . Moreover for $u \in \mathcal{H}$ then $\beta^\epsilon(u) \in \mathcal{H}'$ belongs to the subdifferential of \mathcal{J}^ϵ (as an operator on \mathcal{H}).

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Following the theory of

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we can then prove that the monotone operators β^ϵ tends to the maximal monotone operator β_w in the sense of graph, i.e.,

$$\forall [x, y] \in \beta_w \quad \exists [x^\epsilon, y^\epsilon] \in \beta^\epsilon \quad \text{such that} \quad [x^\epsilon, y^\epsilon] \rightarrow [x, y],$$

where the convergence is intended with respect to the strong topology of $\mathcal{H} \times \mathcal{H}'$.

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Lemma

Let the monotone operator η_n tends to the maximal monotone operator η in the sense of graph (operators on \mathcal{H} into \mathcal{H}'). Let $u_n \rightarrow u$ weakly in \mathcal{H} , $\xi_n \rightarrow \xi$ weakly in \mathcal{H}' , and assume $\xi_n \in \eta_n(u_n)$. If

$$\limsup \langle \xi_n, u_n \rangle \leq \langle \xi, u \rangle,$$

then $\xi \in \eta(u)$.

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These are the ingredients we need!

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Definition

Let $u_0, v_0 \in V$, $z_0 \in \mathcal{Z}$, and $f \in L^2([0, T], V')$. Then (u, z, η) is an energetic solution to (8) if

$$u \in H^1([0, T], V) \cap W^{1, \infty}([0, T], L^2(\Omega)), \quad (18a)$$

$$\dot{u} \in H^1([0, T], H^{-1}(\tilde{\Omega})) \cap BV(0, T; \tilde{H}^{-2}(\Omega)), \quad (18b)$$

$$z \in L^\infty([0, T], \mathcal{Z}) \cap BV(0, T; L^1(\Gamma)), \quad (18c)$$

$$\eta \in \mathcal{H}', \quad (18d)$$

is such that $u(0) = u_0$, $\dot{u}(0) = v_0$, $z(0) = z_0$, and satisfies conditions (a), (a'), (b), (c), and (d) below.

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(a) for all $\varphi \in \mathcal{V}$,

$$\begin{aligned} & - ((\dot{u}, \dot{\varphi})) + (\dot{u}(T), \varphi(T)) + ((\nabla \dot{u}, \nabla \varphi)) + ((\nabla u, \nabla \varphi)) + \langle \eta, [\varphi] \cdot \nu \rangle \\ & = (u_1, \varphi(0)) + \langle f, \varphi \rangle - ((z[u], [\varphi]))^\Gamma. \end{aligned} \quad (19)$$

Energetic formulation of the evolution

(a') for all $t \in [0, T]$ there exists $\eta_t \in \mathcal{H}'$ such that also the local version of (19) holds

$$\begin{aligned} & - ((\dot{u}, \dot{\varphi}))_t + (\dot{u}(t), \varphi(t)) + ((\nabla \dot{u}, \nabla \varphi))_t + ((\nabla u, \nabla \varphi))_t + \langle\langle \eta_t, [\varphi] \cdot \nu \rangle\rangle_t \\ & = (u_1, \varphi(0)) + \langle\langle f, \varphi \rangle\rangle_t - \langle\langle z[u], [\varphi] \rangle\rangle_t^{\Gamma}, \end{aligned} \quad (20)$$

for all $\varphi \in \mathcal{V}_t$. Moreover η_t satisfies the property that, for all $\varphi \in \mathcal{H}_t$ with $\varphi(t) = 0$, we have

$$\langle\langle \eta_t, \varphi \rangle\rangle_t = \langle\langle \eta, \tilde{\varphi} \rangle\rangle, \quad (21)$$

where $\tilde{\varphi}$ is the extension to \mathcal{H} of $\varphi \in \mathcal{H}_{t,0}$ such that $\varphi(s) = 0$ for $s \in [t, T]$.

(b) We have

$$\eta \in \beta_w([u] \cdot \nu), \quad (22)$$

and for all $t \in [0, T]$ it also holds that

$$\eta_t \in \beta_{w,t}([u]_{[0,t]} \cdot \nu).$$

(c) for almost every $x \in \Gamma$ the function $t \mapsto z(t, x)$ is nonincreasing and

$$\text{either } \frac{1}{2} |[u(t, x)]|^2 \leq \alpha(x) \quad \text{or} \quad z(t, x) = 0 \quad \text{for a.e. } x \in \Gamma \quad (23)$$

for all $t \in [0, T]$.

(d) the following energy inequality holds

$$\begin{aligned} & \frac{1}{2} \|\dot{u}(t)\|_H^2 + \int_{\Gamma} j([u(t)] \cdot \nu) dx + \frac{1}{2} \int_{\Gamma} z(t) |[u](t)|^2 dx + \frac{1}{2} \|\nabla u(t)\|^2 \\ & + \int_0^T \|\nabla \dot{u}\|^2 dt - (\alpha, z(t))_{\Gamma} + (\alpha, z_0)_{\Gamma} \leq \\ & \frac{1}{2} \|v_0\|_H^2 + \int_{\Gamma} j([u_0] \cdot \nu) dx + \frac{1}{2} \int_{\Gamma} z_0 |[u_0]|^2 dx + \frac{1}{2} \|\nabla u_0\|^2 + \langle\langle f, \dot{u} \rangle\rangle_t, \end{aligned} \quad (24)$$

for all $t \in [0, T]$.

Energetic formulation of the approximate evolution

In order to prove the existence of an energetic solution we introduce the following approximate evolutions.

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Definition

Let $\epsilon \in (0, 1)$, $u_0, v_0 \in V$, $z_0 \in \mathcal{Z}$, and $f \in L^2([0, T], V')$. Then (u^ϵ, z^ϵ) is an ϵ -approximation of the energetic solution (4) if

$$u^\epsilon \in H^1([0, T], V) \cap W^{1, \infty}([0, T], L^2(\Omega)), \quad (25a)$$

$$\dot{u}^\epsilon \in H^1([0, T], V'), \quad (25b)$$

$$z^\epsilon \in L^\infty([0, T], \mathcal{Z}) \cap BV(0, T; L^1(\Gamma)), \quad (25c)$$

is such that $u^\epsilon(0) = u_0$, $\dot{u}^\epsilon(0) = v_0$, $z^\epsilon(0) = z_0$, and satisfies conditions (a^ϵ) , (b^ϵ) , and (c^ϵ) below.

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(a^ϵ) for every time $t \in [0, T]$, it holds

$$\begin{aligned} & - \langle (\dot{u}^\epsilon, \dot{\varphi}) \rangle_t + \langle \dot{u}^\epsilon(t), \varphi(t) \rangle + \langle (\nabla \dot{u}^\epsilon, \nabla \varphi) \rangle_t + \langle (\nabla u^\epsilon, \nabla \varphi) \rangle_t + \langle \langle \beta^\epsilon([u^\epsilon] \cdot \nu), [\varphi] \cdot \nu \rangle \rangle_t \\ & = \langle u_1, \varphi(0) \rangle + \langle \langle f, \varphi \rangle \rangle_t - \langle \langle z^\epsilon[u^\epsilon], [\varphi] \rangle \rangle_t, \end{aligned} \quad (26)$$

for all $\varphi \in \mathcal{V}$.

Energetic formulation of the approximate evolution

(b^ε) for almost every $x \in \Gamma$ the function $t \mapsto z^\epsilon(t, x)$ is nonincreasing and

$$\text{either } \frac{1}{2} \| [u^\epsilon(t, x)] \|^2 \leq \alpha(x) \quad \text{or} \quad z^\epsilon(t, x) = 0 \quad \text{for a.e. } x \in \Gamma \quad (27)$$

for all $t \in [0, T]$.

(c^ε) the following energy balance holds

$$\begin{aligned} & \frac{1}{2} \|\dot{u}^\epsilon(t)\|_H^2 + \int_\Gamma j^\epsilon([u^\epsilon(t)] \cdot \nu) dx + \frac{1}{2} \int_\Gamma z^\epsilon(t) |[u^\epsilon(t)]|^2 dx + \frac{1}{2} \|\nabla u^\epsilon(t)\|^2 \\ & + \int_0^T \|\nabla \dot{u}^\epsilon\|^2 dt - (\alpha, z^\epsilon(t))_\Gamma + (\alpha, z_0)_\Gamma = \\ & \frac{1}{2} \|v_0\|_H^2 + \int_\Gamma j^\epsilon([u_0] \cdot \nu) dx + \frac{1}{2} \int_\Gamma z_0 |[u_0]|^2 dx + \frac{1}{2} \|\nabla u_0\|^2 + \langle\langle f, \dot{u}^\epsilon \rangle\rangle_t, \end{aligned} \quad (28)$$

for all $t \in [0, T]$.

For all $\epsilon \in (0, 1)$, existence of an approximate solution can be obtained by time discretization and by an implicit Euler scheme. This is standard and we can adapt, for instance, results by

- T. Roubicek, Adhesive contact of visco-elastic bodies and defect measures arising by vanishing viscosity. *SIAM J. Math. Anal.*, 45 (2013), 101-126, and reference therein.

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We want to pass to the limit as $\epsilon \rightarrow 0$. The following Theorem holds true.

Theorem

Let (u^ϵ, z^ϵ) be approximate solutions. Then there exists (u, z, η) energetic solution as in Definition 4 such that, up to a subsequence,

$$u^\epsilon \rightarrow u \quad \text{strongly in } H^1(0, T; L^2(\Omega)) \text{ and weakly in } H^1(0, T; V), \quad (29a)$$

$$\dot{u}^\epsilon \rightharpoonup \dot{u} \quad \text{weakly in } H^1(0, T; H^{-1}(\tilde{\Omega})) \text{ and weakly}^* \text{ in } BV(0, T; \tilde{H}^{-2}(\Omega)), \quad (29b)$$

$$z^\epsilon(t) \rightharpoonup z(t) \quad \text{weakly}^* \text{ in } L^\infty(\Gamma) \text{ for all } t \in [0, T], \quad (29c)$$

$$\beta_\epsilon([u^\epsilon] \cdot \nu) \rightharpoonup \eta \quad \text{weakly in } \mathcal{H}' \text{ and in } \mathcal{V}'. \quad (29d)$$

Sketch of the proof

In order to get the convergences above we should prove suitable apriori estimates for $(u^\epsilon, z^\epsilon, \beta_\epsilon([u^\epsilon] \cdot \nu))$.

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Some estimates are straightforward and follows by the energy balance (c^ϵ) . These are

$$\|\mathbf{u}^\epsilon\|_{H^1(0,t;V)} \leq M,$$

$$\int_\Gamma \mathbf{j}^\epsilon([\mathbf{u}^\epsilon(t)] \cdot \nu) \leq M \text{ for all } t \in [0, T],$$

$$\frac{1}{2} \int_\Gamma |[\mathbf{u}^\epsilon](t)|^2 \mathbf{z}^\epsilon(t) \leq M \text{ for all } t \in [0, T],$$

$$\|\mathbf{z}^\epsilon\|_{L^\infty(0,t;Z)} \leq M,$$

$$\|\mathbf{z}^\epsilon\|_{BV(0,T;L^1(\Gamma))} \leq M.$$

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$$\begin{aligned}\|\mathbf{u}^\epsilon\|_{H^1(0,t;V)} &\leq M, \\ \int_\Gamma j^\epsilon([\mathbf{u}^\epsilon(t)] \cdot \nu) &\leq M \text{ for all } t \in [0, T], \\ \frac{1}{2} \int_\Gamma |[\mathbf{u}^\epsilon](t)|^2 \mathbf{z}^\epsilon(t) &\leq M \text{ for all } t \in [0, T], \\ \|\mathbf{z}^\epsilon\|_{L^\infty(0,t;Z)} &\leq M, \\ \|\mathbf{z}^\epsilon\|_{BV(0,T;L^1(\Gamma))} &\leq M.\end{aligned}$$

Crucial is the following one:

Lemma

For all $\epsilon \in (0, 1)$ it holds

$$\|\beta_\epsilon([\mathbf{u}^\epsilon] \cdot \nu)\|_{L^1(0,T;L^1(\Gamma))} \leq M. \quad (30)$$

Sketch of the proof

This can be obtained letting $\bar{\psi} \in H^{\frac{1}{2}}(\Gamma; \mathbb{R}^d)$ such that $\bar{\psi} \cdot \nu = 1$ on the whole Γ and extending (harmonic) it to an element $\varphi \in V$ which is 0 on Ω_2 , and set $\Psi(t, x) := \varphi(x)$ for all $t \in [0, T]$. Testing the weak equation (a^ϵ) by $u - \delta\Psi$, $\delta > 0$,

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$$\begin{aligned} & (\dot{u}^\epsilon(T), u^\epsilon(T)) - (u_1^\epsilon, u_0^\epsilon) - \int_0^T \|\dot{u}^\epsilon\|_2^2 + \int_{\Omega_1} u^\epsilon(t), \delta\Psi dx - \int_{\Omega_1} u_0^\epsilon, \delta\Psi dx + \int_0^T \|\nabla u^\epsilon\|_2^2 dt \\ & + \frac{1}{2} \|\nabla u^\epsilon(T)\|_2^2 - \frac{1}{2} \|\nabla u_0^\epsilon\|_2^2 + ((\nabla u, \delta\nabla\psi))^{\Omega_1} + (\nabla u^\epsilon(T), \delta\nabla\Psi)^{\Omega_1} - (\nabla u_0^\epsilon, \delta\nabla\Psi)^{\Omega_1} \\ & + \int_0^T \int_\Gamma \beta_\epsilon([u^\epsilon] \cdot \nu)([u^\epsilon] \cdot \nu - \delta) dx dt + ((z^\epsilon, |[u^\epsilon]|^2 - \delta u^\epsilon \cdot \nu)) = \langle\langle f, u^\epsilon \rangle\rangle + \langle\langle f, \delta\Psi \rangle\rangle^{\Omega_1}. \end{aligned}$$

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The previous estimate implies

$$\|\dot{u}^\epsilon\|_{W^{1,1}(0,T;\tilde{H}^{-2}(\Omega))} \leq M, \quad (31)$$

for all $\epsilon \in (0, 1)$.

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Now we employ Helly selection principle combined with a generalized version of Aubin-Lions compactness principle entail the strong convergence

$$u^\epsilon \rightarrow u \quad \text{strongly in } H^1(0, T; L^2(\Omega)) \quad (32)$$

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Another key fact is the following:

Lemma

There holds

$$\|\beta_\epsilon([u^\epsilon] \cdot \nu)\|_{\mathcal{H}'} \leq M, \quad (34)$$

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Using the previous estimate we argue as before using an arbitrary function $\psi \in H^{\frac{1}{2}}(\Gamma; \mathbb{R}^d)$ and suitably extending it to V .

We have then found

$$\beta_\epsilon([u^\epsilon] \cdot \nu) \rightharpoonup \eta,$$

for some $\eta \in \mathcal{H}'$.

Sketch of the proof

We are now ready to prove (b). To this aim we apply Lemma 3, and then we have to check that

$$\limsup_{\epsilon \rightarrow 0} \langle \beta^\epsilon(u^\epsilon), u^\epsilon \cdot \nu \rangle \leq \langle \eta, u \cdot \nu \rangle. \quad (35)$$

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Thanks to the convergences above it is easily seen that (a) holds. Using (26), we write

$$\begin{aligned} \langle \beta^\epsilon([u^\epsilon] \cdot \nu), u^\epsilon \rangle &= \|\dot{u}^\epsilon\|_{L^2(0,T;L^2)}^2 - (\dot{u}^\epsilon(T), u^\epsilon(T)) + (u_1, u_0) - \frac{1}{2} \|\nabla u^\epsilon(T)\|^2 \\ &+ \frac{1}{2} \|\nabla u_0\|^2 - \|\nabla u^\epsilon\|_{L^2(0,T;L^2)}^2 - \int_0^T \int_\Gamma z^\epsilon(t) [u^\epsilon(t)]^2 dx dt + (f, u^\epsilon). \end{aligned} \quad (36)$$

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Taking the lim sup we get

$$\begin{aligned} &\leq \|\dot{\mathbf{u}}\|_{L^2(0,T;L^2)}^2 - (\dot{\mathbf{u}}(T), \mathbf{u}(T)) + (\mathbf{u}_1, \mathbf{u}_0) - \frac{1}{2} \|\nabla \mathbf{u}(T)\|^2 + \frac{1}{2} \|\nabla \mathbf{u}_0\|^2 - \|\nabla \mathbf{u}\|_{L^2(0,T;L^2)}^2 \\ &+ \int_0^T \int_\Gamma z(t) [\mathbf{u}(t)]^2 dx dt + \langle\langle \mathbf{f}, \mathbf{u} \rangle\rangle = \langle\langle \eta, \mathbf{u} \cdot \boldsymbol{\nu} \rangle\rangle, \end{aligned} \quad (37)$$

and the claim follows.

Some Remarks

We have seen that η and η_t coincides with Borel measures concentrated on the set where $[u] \cdot \nu = 0$. Thanks to the fact that

$$\dot{u} \in \text{BV}(0, T; \check{H}^{-2}(\Omega)),$$

it can be proved that $\eta_t \equiv \eta_{\lfloor 0, t \rfloor \times \Gamma}$ outside a set of countable many times.

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In dimension $d = 1$ energy balance holds!

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In dimension $d = 1$ energy balance holds!

The behaviour of the constraint is quite independent of the flow rule of the variable z . For instance, the same behaviour takes place when we add a viscosity term in the flow rule

$$\frac{1}{2} |[u]|^2 + \dot{z} - \alpha \leq 0$$

(S.-G. Schimperna).

THANK YOU FOR ATTENTION!

Some references:

- E. Bonetti, E. Rocca, R. S., G. Schimperna, On the strongly damped wave equation with constraint, preprint arXiv:1503.01911 (2015), 1–21.
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