



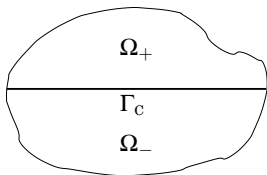
Weierstrass Institute for  
Applied Analysis and Stochastics

# A model for rate-independent, brittle delamination in thermo-visco-elasticity

joint work with Riccarda Rossi

Marita Thomas

## Modeling of delamination along an interface

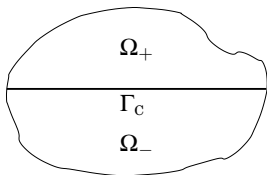


irreversible crack evolution along a prescribed surface

$\Gamma_C$ : (flat) interface with evolving delamination  
(= crack initiation & growth)

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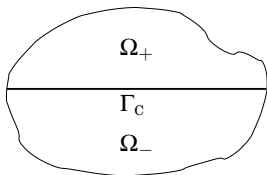
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Modeling approach: **Continuum damage mechanics**: [Frémond82,87]

delamination variable  $z : [0, T] \times \Gamma_C \rightarrow [0, 1]$  volume fraction of **active** bonds

$$\text{crack}(t) := \{x \in \Gamma_C, z(t, x) = 0\} \quad \forall t_1 < t_2 : z(t_2) \leq z(t_1) \text{ a.e. on } \Gamma_C$$

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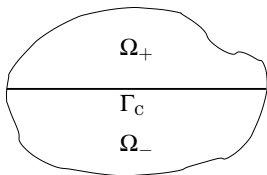
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penalized by energy term

[Kočvara/Mielke/Roubíček06, Roubíček/Scardia/Zanini09, Bonetti/Bonfanti/Rossi08,09]

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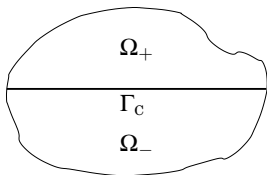
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**nonpenetration** condition:  $\llbracket u \rrbracket \cdot \mathbf{n} \geq 0$  a.e. on  $\Gamma_C$



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### Plan of the talk:

1. Mathematical modeling of delamination
  - Fully rate-independent evolution of brittle delamination: energetic formulation
  - Extension of the model by rate-dependent effects
2. Adapted energetic formulation & suitable regularizations
3. Main result & mathematical tools

State variable  $q = (u, z)$ :

$u : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  displacement,  $e(u) = \frac{1}{2}(\nabla u + \nabla u^\top)$  lin. strain

$z : [0, T] \times \Gamma_c \rightarrow [0, 1]$  delamination variable

Energy functional

$$\Phi(t, q) := \int_{\Omega \setminus \Gamma_c} W(e(u)) dx + \int_{\Gamma_c} (I_{\{z[[u]]=0\}}(\llbracket u \rrbracket, z) + I_{[0,1]}(z) + I_{\{\llbracket u \rrbracket \cdot n \geq 0\}}(\llbracket u \rrbracket) - a_0 z) ds - \langle F(t), u \rangle$$

indicator function of set/constraint  $C$ :  $I_C(y) := \begin{cases} 0 & \text{if } y \in C \\ \infty & \text{otherwise} \end{cases}$

## Rate-independent evolution of brittle delamination

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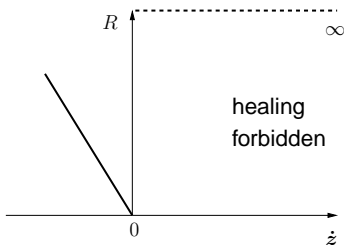
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Dissipation potential:

$$\mathcal{R}_1(\dot{z}) = \int_{\Gamma_c} R_1(\dot{z}(x)) ds \quad R_1(\dot{z}) := \begin{cases} a_1 |\dot{z}| & \text{if } \dot{z} \leq 0 \\ \infty & \text{else} \end{cases}$$

with  $a_1 > 0$





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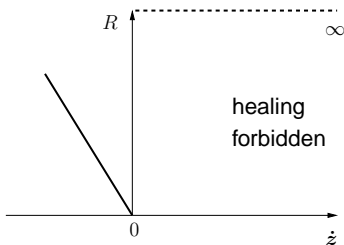
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Rate-independence  $\Leftrightarrow$  1-homogeneity:

$$\mathcal{R}_1(0) = 0 \text{ and } \forall \lambda > 0 \forall v : \mathcal{R}_1(\lambda v) = \lambda \mathcal{R}_1(v)$$



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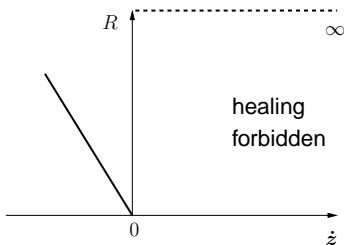
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$\Downarrow$

$$\text{Dissipation distance: } \mathcal{D}_1(z_1, z_2) = \mathcal{R}_1(z_2 - z_1)$$



Subdifferential formulation:

Find  $q \in \mathcal{Q}$  such that  $q(0) = q_0$  and  $0 \in \partial_q \Phi(t, q) + \partial_{\dot{q}} \mathcal{R}_1(\dot{q})$

Subdifferential formulation:

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refers to the system (formally):

momentum balance for  $u$  in  $(0, T) \times \Omega \setminus \Gamma_C$ :

$$-\operatorname{div} D_e W(e(u)) = F \quad + \text{BCs on } (0, T) \times \partial\Omega + \text{IC}$$

& flow rule for  $z$  on  $(0, T) \times \Gamma_C$ :

$$0 \in \partial_{\dot{z}} \mathcal{R}_1(\dot{z}) + \partial_z I_{\{z[[u]]=0\}}(\llbracket u \rrbracket, z) + \partial_z I_{[0,1]}(z) - a_0 \quad + \text{IC}$$

& constraint for  $(u, z)$  on  $(0, T) \times \Gamma_C$ :

$$\llbracket D_e W(e(u)) \rrbracket \mathbf{n} = 0$$

$$0 \in \partial_u I_{[z[[u]]=0]}(\llbracket u \rrbracket, z) + \partial_u I_{\{[[u]] \cdot \mathbf{n} \geq 0\}}(\llbracket u \rrbracket) + D_e W(e(u)) \mathbf{n}$$

due to brittle constraint and nonpenetration

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Alternative, weaker problem formulation due to 1-homogeneity of  $\mathcal{R}_1$

Find an **energetic solution** for  $(\mathcal{Q}, \Phi, \mathcal{R}_1)$

**Definition** [Mielke&Co]:  $q : [0, T] \rightarrow \mathcal{Q}$  is an **energetic solution** to  $(\mathcal{Q}, \Phi, \mathcal{R}_1)$ , if for all  $t \in [0, T]$  it holds  $\partial_t \Phi(\cdot, q(\cdot)) \in L^1((0, T))$ ,  $\Phi(t, q(t)) < \infty$  and:

$$\left\{ \begin{array}{l} \text{(S) Stability : for all } \tilde{q} \in \mathcal{Q} : \Phi(t, q(t)) \leq \Phi(t, \tilde{q}) + \mathcal{R}_1(\tilde{z} - z(t)), \\ \text{(E) Energy balance : } \Phi(t, q(t)) + \text{Diss}_{\mathcal{R}_1}(z, [0, t]) = \Phi(0, q(0)) + \int_0^t \partial_t \Phi(\xi, q(\xi)) d\xi, \end{array} \right.$$

where  $\text{Diss}_{\mathcal{R}_1}(z, [s, t]) := \sup_{\text{all part. of } [s, t]} \sum_{j=1}^N \mathcal{R}_1(z(\xi_j) - z(\xi_{j-1}))$ .

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[Roubíček/Scardia/Zanini09]: Existence of energetic solutions for brittle delamination by approximation with adhesive contact:  $\frac{k}{2} z |[[u]]|^2 \rightarrow I_{\{z[[u]]=0\}}([[u]], z)$  as  $k \rightarrow \infty!$

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Extention of the model:

brittle, rate-independent delamination & nonpenetration

& visco-elastic material & thermal effects

Analogous strategy as in the fully rate-independent case:

adhesive model from [Rossi/Roubíček10]  $\xrightarrow{?}$  brittle model

## Brittle delamination & nonpenetration

state variables:  $u : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  displacement,  $e(u) = \frac{1}{2}(\nabla u + \nabla u^\top)$  lin. strain  
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$(u, z)$  coupled in system given by

momentum balance( $e(u)$  )

& flow rule( $\dot{z}$ )

& constraint( $z, \llbracket u \rrbracket$ ) on  $\Gamma_C$   
due to brittle constraint & nonpenetration

+ BCs + ICs

rate-independent evolution of  $z$

$\Rightarrow$  energetic formulation via global stability & energy balance



## Brittle delamination & nonpenetration & viscosity & therm. effects

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 $\theta : [0, T] \times \Omega \rightarrow (0, \infty)$  absolute temperature

$(u, z, \theta)$  coupled in system given by

momentum balance( $e(u), e(\dot{u}), \theta$ )  
& heat equation( $e(u), e(\dot{u}), \dot{\theta}, \theta$ )  
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**But:** adapted energetic formulation of system in terms of 4 conditions [Roubíček10]:

1. weak momentum balance (for  $u$ )
2. weak enthalpy (in)equality (for  $\theta$ )
3. semistability (for  $z$ )
4. mechanical energy 'balance'

adhesive model from [Rossi/Roubíček10]  $\xrightarrow{\checkmark}$  brittle model

### 2. Adapted energetic formulation & sufficiently regularized models

### 3. Main result and tools

$$c_v(\theta)\dot{\theta} + \operatorname{div} \mathbb{J}(e(u), \theta) = 2R_2(e(\dot{u})) - \theta \mathbb{C} \mathbb{E} e(\dot{u}) + H \quad \text{in } [0, T] \times \Omega \setminus \Gamma_c$$

- $H$  external heat source,  $\mathbb{C}$ ,  $\mathbb{E}$  sym., pos. def. fourth order tensors
- Fourier's law for heat flux:  $\mathbb{J}(e, \theta) = -\mathbb{K}(e, \theta) \nabla \theta$
- heat capacity  $c_v(\theta)$
- viscous dissipation:  $R_2(\dot{e}) := |\dot{e}|^2$

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Idea: Use time-discretization to prove existence of energetic sol.s for the full PDE-system

**Problem:** nonlinearity  $c_v(\theta)\dot{\theta}$

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Way out: **enthalpy-transformation** [Roubíček10]:

$$\text{enthalpy } w = w(\theta) := \int_0^\theta c_v(\xi) d\xi, \quad \theta = \Theta(w), \quad \tilde{\mathbb{K}}(e, w) = \mathbb{K}(e, \Theta(w)) / c_v(\Theta(w)).$$

Reformulate full PDE-system in terms of  $w$

$$\dot{w} - \operatorname{div}(\tilde{\mathbb{K}}(e(u), w)\nabla w) = 2R_2(e(\dot{u})) - \Theta(w)\mathbb{C}\mathbb{E}e(\dot{u}) + H \quad \text{in } [0, T] \times \Omega \setminus \Gamma_C$$

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+ BCs on  $\partial\Omega$  + conditions on  $\Gamma_C$  involving dissipation  $R_1(\dot{z})$

leads to **weak enthalpy (in)equality**:

$$\langle \zeta(T), w(T) \rangle + \int_Q \tilde{\mathbb{J}}(e(u), w) \cdot \nabla \zeta - w \dot{\zeta} \, dxdt + \int_{\Sigma_C} \eta([u], z)[\Theta(w)][\zeta] \, dsdt$$

$$\left\{ \begin{array}{l} = \\ \geq \end{array} \right\} \int_Q (2R_2(e(\dot{u}))\zeta - \Theta(w)\mathbb{C}\mathbb{E} : e(\dot{u})\zeta) \, dxdt + \int_{\Sigma_C} \frac{1}{2}(\zeta|_{\Gamma_C}^+ - \zeta|_{\Gamma_C}^-) \, d\xi_z^S(s, T)$$

$$+ \int_Q H \zeta \, dxdt + \int_{\Omega \setminus \Gamma_C} w_0 \zeta(0) \, dx$$

for all testfcts  $\zeta \geq 0$  a.e.

adhesive contact ' $=$ ', brittle delamination ' $\geq$ '

$d\xi_z^S(s, T)$  is a measure induced by dissipation  $R_1(\dot{z})$



## Weak formulation of the momentum balance $(e(u), e(\dot{u}), \theta)$

---

$$-\operatorname{div} \sigma(u, \dot{u}, \theta) = F \quad \text{in } [0, T] \times \Omega \setminus \Gamma_C \quad (F \text{ applied bulk force})$$

stress  $\sigma(u, \dot{u}, \theta)$  features **viscous** response and **thermal effects** (Kelvin-Voigt rheology)

$$\sigma(u, \dot{u}, \theta) := \mathbf{D}_e \mathbf{R}_2(e(\dot{u})) + \mathbf{D}_e W_p(e(u)) + \mathbb{C}(e(u) - \mathbb{E}\theta)$$

**viscous** dissipation:  $\mathbf{R}_2(\dot{e}) := |\dot{e}|^2$

bulk energy density:  $W(e, \theta) := W_p(e) + \frac{1}{2}(e(u) - \mathbb{E}\theta) : \mathbb{C} : (e(u) - \mathbb{E}\theta)$

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+ BCs + constraint  $(z, \llbracket u \rrbracket)$  on  $\Gamma_C$ :

$$0 \in \partial_u I_{\{\llbracket u \rrbracket \cdot \mathbf{n} \geq 0\}}(u) + \sigma(u, \dot{u}, \theta) \mathbf{n} + \partial_u I_{\{z \llbracket u \rrbracket = 0\}}(z, u)$$

## Weak formulation of the momentum balance $(e(u), e(\dot{u}), \theta)$

$$-\operatorname{div} \sigma(u, \dot{u}, \theta) = F \quad \text{in } [0, T] \times \Omega \setminus \Gamma_C$$

stress  $\sigma(u, \dot{u}, \theta)$  features viscous response and thermal effects (Kelvin-Voigt rheology)

$$\sigma(u, \dot{u}, \theta) := D_e R_2(e(\dot{u})) + D_e W_p(e(u)) + \mathbb{C}(e(u) - \mathbb{E}\theta)$$

viscous dissipation:  $R_2(\dot{e}) := |\dot{e}|^2$

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leads to **weak momentum balance** as a variational inequality for a.a.  $t \in (0, T)$ :

$\llbracket u(t) \rrbracket \cdot \mathbf{n} \geq 0$ ,  $z(t) \llbracket u(t) \rrbracket = 0$  on  $\Gamma_C$  and

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double constraint  $\Rightarrow$  approximate **brittle constraint**  $z(t) \llbracket v \rrbracket = 0$  by **adhesive contact**

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$$0 \in \partial_u I_{\{\llbracket u \rrbracket \cdot \mathbf{n} \geq 0\}}(u) + \sigma(u, \dot{u}, \theta) \mathbf{n} + kz \llbracket u \rrbracket$$

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approximate **brittle constraint**  $z(t) \llbracket v \rrbracket = 0$  by **adhesive contact**

$$0 \in \partial_{\dot{z}} R_1(\dot{z}) + \partial_z \phi^s(z, \llbracket u \rrbracket) \quad \text{on } \Gamma_c$$

- rate-independent dissipation  $R_1(\dot{z}) = -a_1 \dot{z} + I_{(-\infty, 0]}(\dot{z})$
- surface energy density  $\phi^s(z, \llbracket u \rrbracket) = -a_0 z + I_{[0, 1]}(z) + I_{[z \llbracket u \rrbracket = 0]}(z, \llbracket u \rrbracket)$

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weak formulation: **semistability**

$$\forall t \in [0, T], \forall \text{ testfcts } \tilde{z}: \quad \Phi^s(z(t), \llbracket u(t) \rrbracket) \leq \Phi^s(\tilde{z}, \llbracket u(t) \rrbracket) + \mathcal{R}_1(\tilde{z} - z(t))$$

'partial' stability condition, since  $u(t)$  (energetic sol.) is fixed!

Recall stability in the (fully) rate-independent setting:

$$\forall t \in [0, T], \forall \text{ testfcts } (\tilde{u}, \tilde{z}): \quad \mathcal{E}(t, u(t), z(t)) \leq \mathcal{E}(t, \tilde{u}, \tilde{z}) + \mathcal{R}_1(\tilde{z} - z(t))$$

$$\forall t \in [0, T], \forall \text{testfcts } \tilde{z}: \quad \Phi^s(z(t), \llbracket u(t) \rrbracket) \leq \Phi^s(\tilde{z}, \llbracket u(t) \rrbracket) + \mathcal{R}_1(\tilde{z} - z(t))$$

$$\phi^s(z, \llbracket u \rrbracket) = -a_0 z + I_{[0,1]}(z) + I_{\{z \llbracket u \rrbracket = 0\}}(z, \llbracket u \rrbracket) \text{ for brittle delamination}$$



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Regularizations:

1. adhesive contact:  $\phi^s(z, \llbracket u \rrbracket) = -a_0 z + I_{[0,1]}(z) + \frac{k}{2} z |\llbracket u \rrbracket|^2$

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$$\text{SBV}(\Gamma_c, \{0, 1\}) := \{z: \Gamma_c \rightarrow \{0, 1\}, z \text{ characteristic fct. of set } Z \subset \Gamma_c \text{ with } P(Z, \Gamma_c) < \infty\}$$

$$\Phi^s(z, \llbracket u \rrbracket) + \mathcal{G}_b(z)$$

$$\mathcal{G}_b(z) := \text{b}P(Z, \Gamma_c) \text{ perimeter of } Z (= \text{total variation of } z)$$



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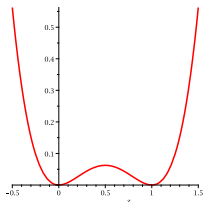
$$\Phi^s(z, \llbracket u \rrbracket) + \mathcal{G}_b(z)$$

$\mathcal{G}_b(z) := bP(Z, \Gamma_C)$  perimeter of  $Z$  (= total variation of  $z$ )

3. Modica-Mortola approximation:

$$\mathcal{G}_m(z) := \begin{cases} \int_{\Gamma_C} (m^2 z^2 (1-z)^2 + \frac{1}{m^2} |\nabla z|^2) dx & \text{if } z \in H^1(\Omega, [0, 1]) \\ \infty & \text{otherwise} \end{cases}$$

$$\mathcal{G}_m \xrightarrow{\Gamma} \mathcal{G}_b \text{ as } m \rightarrow \infty$$



[Giacomini05] Volume damage  $\rightarrow$  Francfort-Marigo crack model

$$\forall t \in [0, T], \forall \text{ testfcts } \tilde{z}: \quad \Phi^s(z(t), \llbracket u(t) \rrbracket) \leq \Phi^s(\tilde{z}, \llbracket u(t) \rrbracket) + \mathcal{R}_1(\tilde{z} - z(t))$$

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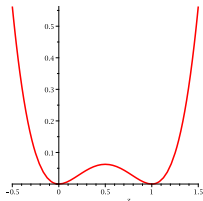
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$\mathcal{G}_m \xrightarrow{\Gamma} \mathcal{G}_b$  as  $m \rightarrow \infty$  adapted to stability cond. for unidirectional  $\mathcal{R}_1$ : [Th11]



Energy terms:

- mechanical energy  $\Phi(u, z) = \Phi^{\text{bulk}}(u, z) + \Phi^{\text{surf}}(z, \llbracket u \rrbracket)$
- mechanical bulk energy  $\Phi^{\text{bulk}}(u, z) = \int_{\Omega \setminus \Gamma_C} W_p(e(u)) + \frac{1}{2} e(u) : C : e(u) \, dx$
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$$\Phi^{\text{surf}}(z, \llbracket u \rrbracket) := \int_{\Gamma_C} (-a_0 z + I_{[0,1]}(z) + J_k(z, \llbracket u \rrbracket) + I_{\{\llbracket u \rrbracket \cdot n \geq 0\}}(\llbracket u \rrbracket)) \, ds + \mathcal{G}(z)$$

$$J_k(z, \llbracket u \rrbracket) = \begin{cases} \frac{k}{2} z |\llbracket u \rrbracket|^2 & \text{adhesive, } k \in \mathbb{N} \\ I_{\{z \llbracket u \rrbracket = 0\}}(z, \llbracket u \rrbracket) & \text{brittle, } k = \infty \end{cases} \quad \mathcal{G}(z) = \begin{cases} \mathcal{G}_m(z) & \text{Modica-Mortola} \\ \mathcal{G}_b(z) & \text{SBV (perimeter)} \end{cases}$$

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Mechanical energy 'balance' for a.a.  $t \in (0, T)$ :

$$\Phi(u(t), z(t)) + \int_0^t \int_{\Omega \setminus \Gamma_C} 2R_2(e(\dot{u})) \, dx \, d\xi + \mathcal{R}_1(z(t) - z(0))$$

$$\left\{ \begin{array}{l} = \\ \leq \end{array} \right\} \Phi(u(0), z(0)) + \int_0^t \int_{\Omega \setminus \Gamma_C} \Theta(w) \mathbb{C} \mathbb{E} : e(\dot{u}) \, dx \, d\xi + \int_0^t \int_{\Omega \setminus \Gamma_C} F(t) \cdot \dot{u} \, dx \, d\xi$$

### 3. Results: Approximation procedure (viscous, $\theta$ -dependent setting)

$$\Phi_{km}^{\text{surf}}(z, \llbracket u \rrbracket) := \int_{\Gamma_C} (-a_0 z + I_{[0,1]}(z) + I_{\{\llbracket u \rrbracket \cdot n \geq 0\}}(\llbracket u \rrbracket) + \frac{k}{2} z |\llbracket u \rrbracket|^2) \, ds + \mathcal{G}_m(z)$$

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Limit passage:

Modica-Mortola **adhesive** contact  $\rightarrow$  **SBV-adhesive** contact

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Limit passage  $k \rightarrow \infty$ :

**SBV-adhesive** contact  $\rightarrow$  **SBV-brittle** delamination

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**Main difficulty:** Limit passage in weak momentum balance!

weak momentum balance for SBV-adhesive delamination f.a.a.  $t \in (0, T)$ :

$$\begin{aligned} \llbracket u_k(t) \rrbracket \cdot \mathbf{n} \geq 0, \quad z_k(t) \llbracket u_k(t) \rrbracket \leq 0 \quad \text{on } \Gamma_C \quad \text{and} \\ \int_{\Omega \setminus \Gamma_C} (\mathbb{D}_e W(e(u_k(t)), \Theta(w_k(t))) + \mathbb{D}_e R_2(e(\dot{u}_k(t)))) : e(v - u_k(t)) dx \\ + \int_{\Gamma_C} k z_k(t) \llbracket u_k(t) \rrbracket \cdot \llbracket v - u_k(t) \rrbracket ds \\ \geq + \int_Q F(t) \cdot (v - u_k(t)) dx \end{aligned}$$

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**Problem:**  $z(t)[[v]] = 0$ ,  $z_k \xrightarrow{*} z$  in  $\text{SBV}(\Gamma_c, \{0, 1\})$ , but  $\int_{\Gamma_c} kz_k(t)[[u_k(t)]] \cdot [[v]] \rightarrow ???$

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**Idea:** construct recovery sequence  $(v_k)_{k \in \mathbb{N}}$  for testfct.  $v$  such that

$$\forall k \in \mathbb{N}: \quad z_k(t) \llbracket v_k \rrbracket = 0 \text{ a.e. on } \Gamma_C \quad \text{and} \quad v_k \rightarrow v \text{ strongly in } W^{1,p}(\Omega \setminus \Gamma_C, \mathbb{R}^d).$$

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**Problem:**  $z(t) \llbracket v \rrbracket = 0$ ,  $z_k \xrightarrow{*} z$  in  $\text{SBV}(\Gamma_C, \{0, 1\})$ , but  $\int_{\Gamma_C} kz_k(t) \llbracket u_k(t) \rrbracket \cdot \llbracket v \rrbracket \rightarrow ???$

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weak momentum balance for SBV-adhesive delamination f.a.a.  $t \in (0, T)$ :

$$\llbracket u_k(t) \rrbracket \cdot \mathbf{n} \geq 0, \quad z(t) \llbracket u(t) \rrbracket = 0 \text{ on } \Gamma_C \text{ and}$$

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**Reason** for  $v_k \rightarrow v$  strongly in  $W^{1,p}$ : Mosco-conv. of energy fct.  $\Rightarrow$  G-conv. of derivative



## Recovery sequence & support property

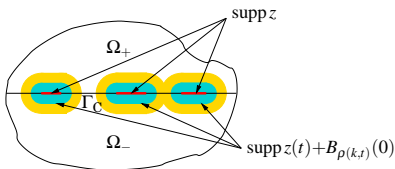
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**Tool: Support convergence:**  $\forall t \in [0, T]$

$\text{supp } z_k(t) \subset \text{supp } z(t) + B_{\rho(k,t)}(0)$  for all  $k \in \mathbb{N}$  and  $\rho(k,t) \rightarrow 0$  as  $k \rightarrow \infty$



$v_k(t) \in W^{1,p}(\Omega \setminus \Gamma_C, \mathbb{R}^d)$  s.th.

$v_k(t) = 0$  in  $\text{supp } z(t) + B_{\rho(k,t)}(0)$ ,

$v_k(t) = v(t)$  in  $\Omega \setminus \text{supp } z(t) + B_{2\rho(k,t)}(0)$

$\llbracket v_k(t) \rrbracket \cdot n \geq 0$  on  $\Gamma_C$

[Mielke/Roubiček/Th10]: Let  $p > d$ . Then,  $v_k(t) \rightarrow v(t)$  strongly in  $W^{1,p}(\Omega \setminus \Gamma_C, \mathbb{R}^d)$ .

([Lewis88]: Hardy's inequality)

## Support convergence

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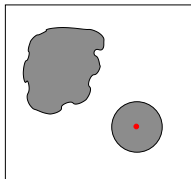
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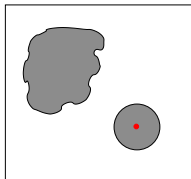
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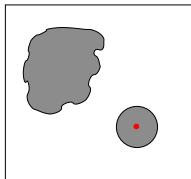
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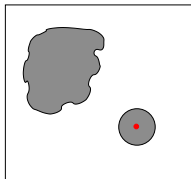
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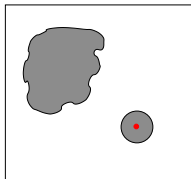
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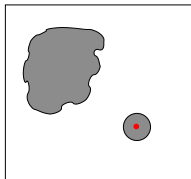
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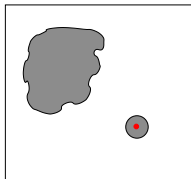
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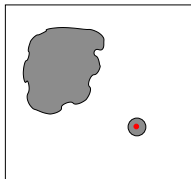
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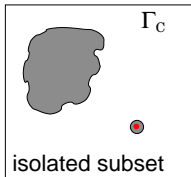
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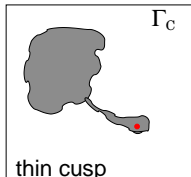
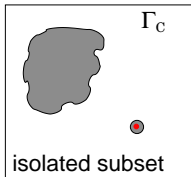
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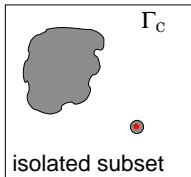
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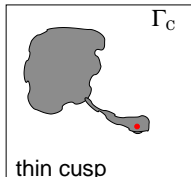
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**Exclude arbitrarily small sets by semistability!**



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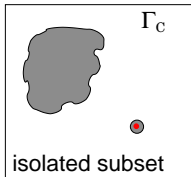
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$$\Phi_k(z_k, \llbracket u_k \rrbracket) = \int_{\Gamma_C} (-a_0 z_k + \frac{k}{2} z_k |\llbracket u_k \rrbracket|^2) ds + bP(Z_k, \llbracket u_k \rrbracket)$$



**Exclude arbitrarily small sets by semistability!**

$z_k$  semistable charact. fct. of  $Z_k$ ,  $A \subset Z_k$  isolated

test semistability with  $\tilde{z}$  charact. fct. of  $Z_k \setminus A$ :

$$\Phi_k(z_k, \llbracket u_k \rrbracket) \leq \Phi_k(\tilde{z}, \llbracket u_k \rrbracket) + \mathcal{R}_1(\tilde{z} - z_k)$$

$$\Rightarrow bP(A, \Gamma_C) \leq (a_0 + a_1) \mathcal{L}^{d-1}(A)$$

$$\frac{b}{(a_0 + a_1)} \leq \frac{\mathcal{L}^{d-1}(A)}{P(A, \Gamma_C)} \leq c_{d-1} \mathcal{L}^{d-1}(A)^{1/(d-1)}$$

isoperimetric inequality



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R. ROSSI AND M. THOMAS:

*From an adhesive to a brittle delamination model in thermo-visco-elasticity,*  
WIAS-Preprint 1692.

Thank You!