

# On a conservative isogeometric scheme for the wave equation

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# Introduction

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## Model problem

Let  $\Omega = \mathcal{F}(\hat{\Omega})$ , where  $\mathcal{F}$  is an isogeometric map, and  $\hat{\Omega} = [0, 1]^d$ , with  $d \in \mathbb{N}$ . Given  $T \in \mathbb{R}^+$ , we consider:

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$$\begin{cases} \mathbf{v}_t = c \nabla \phi & \text{in } \Omega \times [0, T], \\ \phi_t = \operatorname{div}(c \mathbf{v}) & \text{in } \Omega \times [0, T]. \end{cases}$$

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The problem will be find  $\mathbf{v} \in V = \mathbf{H}(c, \operatorname{div}; \Omega)$  and  $\phi \in Q = L^2(\Omega)$  such that:

$$\int_{\Omega} \mathbf{v}_t \cdot \mathbf{w} \, dx = - \int_{\Omega} \operatorname{div}(c \mathbf{w}) \phi \, dx + \underbrace{\int_{\partial \Omega} c \phi \mathbf{w} \cdot \mathbf{n} \, d\Gamma}_{=0} \quad \forall \mathbf{w} \in V,$$

$$\int_{\Omega} \phi_t \psi \, dx = \int_{\Omega} \operatorname{div}(c \mathbf{v}) \psi \, dx, \quad \forall \psi \in Q.$$

# Isogeometric framework

The isogeometric map  $\mathcal{F} : \hat{\Omega} \rightarrow \Omega$ , is a parameterization of the geometry of the physical domain.

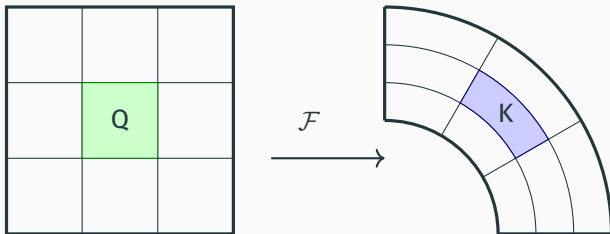
# Isogeometric framework

The isogeometric map  $\mathcal{F} : \hat{\Omega} \rightarrow \Omega$ , is a parameterization of the geometry of the physical domain. Usually indicated by

$$\mathcal{F} := \sum_{i \in J} c_i \hat{B}_{i,p}.$$

a linear combination of B-splines (or NURBS) of degree  $p$ .

## Example



**Figure 1:** Mesh  $\hat{\mathcal{M}}$  in the parametric domain, and its image  $\mathcal{M}$  on the physical domain.



# Univariate B-splines

## Example

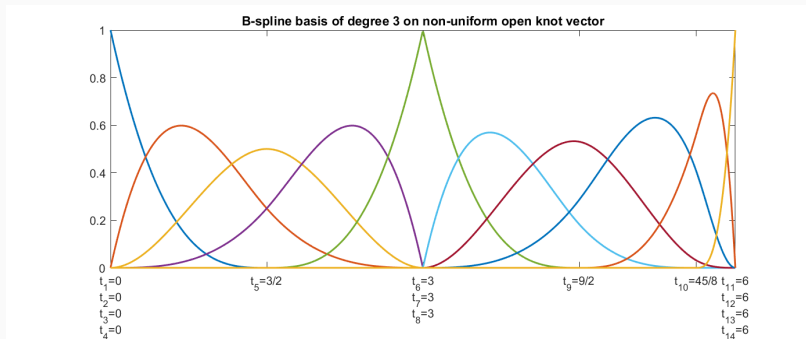


Figure 2: An example of univariate B-spline basis functions.

## Project the equations

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## Modified problem

We introduce  $\Pi^1 : V \rightarrow V_h$  and  $\Pi^2 : Q \rightarrow Q_h$ , and consider:

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The modified problem reads: find  $\mathbf{v} \in V$  and  $\phi \in Q$  such that:

$$\begin{aligned} \int_{\Omega} \mathbf{v}_t \cdot \mathbf{w} \, d\mathbf{x} &= - \int_{\Omega} \Pi^2(\operatorname{div}(c\mathbf{w}))\phi \, d\mathbf{x}, \quad \forall \mathbf{w} \in V, \\ \phi_t &= \Pi^2(\operatorname{div}(c\mathbf{v})). \end{aligned} \tag{1}$$

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We retrieve the conservation of total Energy, that is:

$$E(t) := \frac{1}{2} \int_{\Omega} |\mathbf{v}|^2 + \phi^2 \, d\mathbf{x} = E_0.$$

# How to choose $\Pi^i$ ?

We ask  $\Pi^1$  and  $\Pi^2$  to commute with the following diagram:

$$\begin{array}{ccc} \mathbf{H}(c, \operatorname{div}; \Omega) & \xrightarrow{\operatorname{div}} & L^2(\Omega) \\ \Pi^1 \downarrow & & \downarrow \Pi^2 \\ V_h & \xrightarrow{\operatorname{div}} & Q_h, \end{array} \quad (2)$$

that is

$$\Pi^2(\operatorname{div}(c\mathbf{v})) = \operatorname{div}(\Pi^1(c\mathbf{v})).$$

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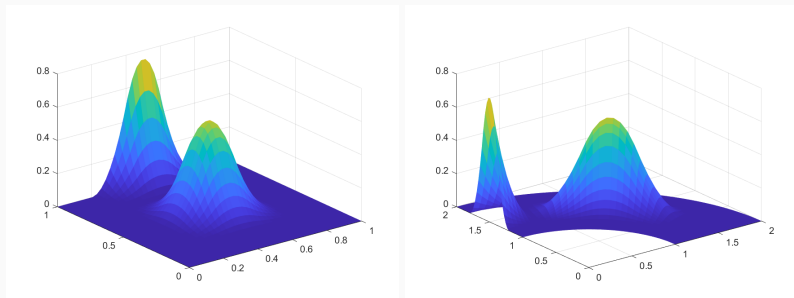
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## Isogeometric De Rham complex

- $V_h$  and  $Q_h$  are suitable pushforwards of spline spaces over  $\hat{\Omega}$ ;
- $\Pi^i$  are suitable pullbacks of Tensor-Product univariate quasi-interpolants  $\hat{\pi}_p$ ; [Beirão da Veiga et al., 2014]
- We took the quasi-interpolants described in [Lee et al., 2000]

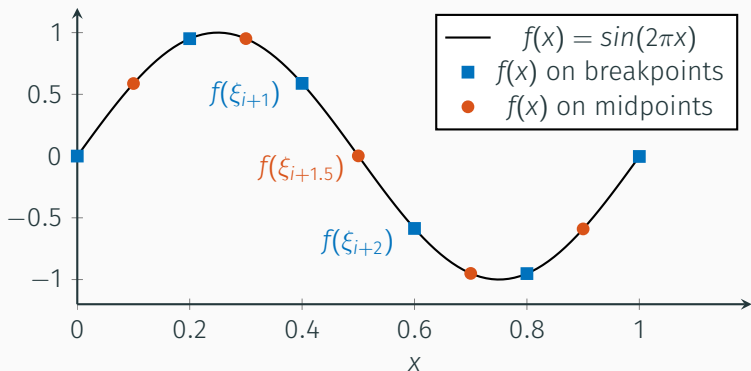
## Push-forward:



**Figure 3:** *Left:* two multivariate B-splines over the parametric domain  $\hat{\Omega}$ . *Right:* push-forward of the two B-splines with the Piola transformations.



## Univariate quasi-interpolants from [Lee et al., 2000]:



**Figure 4:** Example of point-wise evaluation of  $f(x) = \sin(2\pi x)$  for projection with  $\hat{\pi}_2$ . The explicit formula is  $\lambda_{i,2}(f) = -\frac{1}{2}f(\xi_{i+1}) + 2f(\xi_{i+1.5}) - \frac{1}{2}f(\xi_{i+2})$ .

# Semi-discrete mixed formulation

The space semi-discretization of the modified problem (1) is: find  $\mathbf{v} \in V_h$  and  $\phi \in Q_h$ , such that

$$\begin{aligned} \int_{\Omega} \mathbf{v}_t \cdot \mathbf{w}_h \, d\mathbf{x} &= - \int_{\Omega} \operatorname{div}(\Pi^1(c\mathbf{w}_h))\phi \, d\mathbf{x}, \quad \forall \mathbf{w}_h \in V_h, \\ \phi_t &= \Pi^2(\operatorname{div}(c\mathbf{v})). \end{aligned} \tag{3}$$

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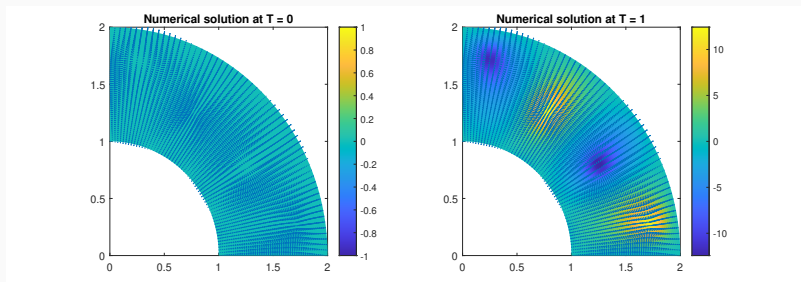
## Note:

- This semi-discretization + Crank-Nicolson in time is Energy preserving;
- We are changing the test functions !

## Numerical results

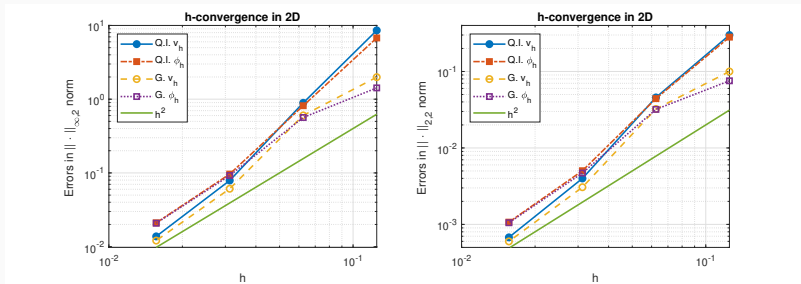
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## Solutions:



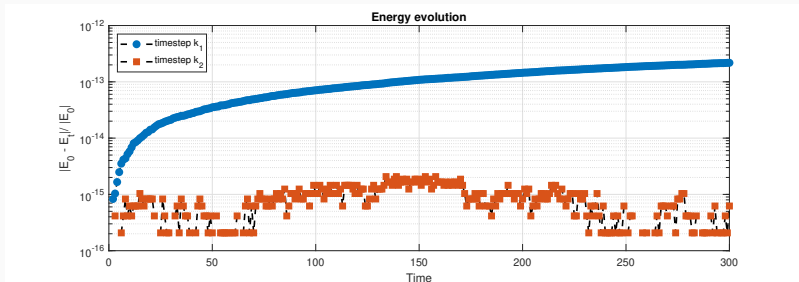
Numerical solution for Dirichlet homogeneous boundary conditions at  $T = 1$ . Mesh width  $h = 0.0156$  and  $k = 5e - 04$ . Coefficient  $c = \sin(2\pi x_1)\sin(2\pi x_2) + 2$ . Solutions computed with GeoPDEs [Vázquez, 2016].

## Convergence rates:



*Left:* errors in  $\|\cdot\|_{\infty,2}$  norm for solutions with (Q.I.) and (G) methods with homogeneous Dirichlet boundary conditions. *Right:* errors with  $\|\cdot\|_{2,2}$  norm for the same problems.

## Energy conservation:



Energy conservation plots for Dirichlet homogeneous boundary conditions. Mesh width  $h = 0.0312$ , while  $T = 300$  and two different partitions with  $k_1 = 0.2$  and  $k_2 = 0.01$ .

## Conclusive remarks

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## Relevant remarks

- We have a new discretization scheme that hides the (non-constant) coefficients into the test functions;
- We achieve optimal convergence rates as in a standard Galerking discretization;
- We preserved the total Energy of the system for long time simulations;
- To assemble the matrices, we have to compute the projections  $\Pi^1(c\mathbf{w}_h)$  letting vary  $\mathbf{W}_h$  in the set of basis functions of  $V_h$ . This projections are local.




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## Open problems:

- Analytical error estimates?
- Minimal hypothesis on  $c$ ?
- Parallel computation?

## References

-  Beirão da Veiga, L., Buffa, A., Sangalli, G., and Vázquez, R. (2014). **Mathematical analysis of variational isogeometric methods.** *Acta Numerica*, 23:157.
-  Lee, B.-G., Lyche, T., and Mørken, K. (2000). **Some examples of quasi-interpolants constructed from local spline projectors.** *Mathematical methods for curves and surfaces: Oslo*, pages 243–252.
-  Vázquez, R. (2016). **A new design for the implementation of isogeometric analysis in Octave and Matlab: GeoPDEs 3.0.** *Computers and Mathematics with Applications*, 72(3):523–554.



Thank  
You!